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Action and perception are tightly coupled. This has been developed most comprehensively with respect to vision (active vision) where an agent (animal, robot, human, camera mount) changes position to improve the view of a specific object, or where an agent uses movement to perceive the environment (e.g., a robot

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Active perception - Wikipedia

As outlined in a research paper presented at the 2019 International Conference on Robotics and Automation (ICRA) in Montreal, the project ' s active perception approach is the first in the world to focus on real-time grasping by stepping away from a static camera position or fixed data collecting routines.

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Overview . The Interactive Perception and Robot Learning Lab is part of the Stanford AI Lab at the Computer Science Department. We seek to understand the underlying principles of robust sensorimotor coordination by implementing them on robots.

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